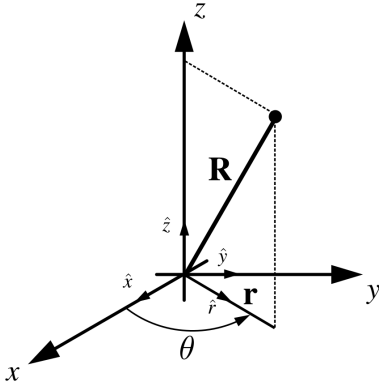


Cylindrical coordinates



Cartesian \longleftrightarrow Cylindrical

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$z = z$$

$$\mathbf{R} = r \hat{\mathbf{r}} + z \hat{\mathbf{z}}$$

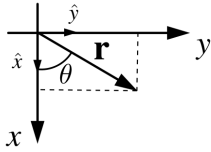
$$\mathbf{R} = r \hat{\mathbf{r}} + z \hat{\mathbf{z}}$$

$$r = \sqrt{x^2 + y^2}$$

If a vector \mathbf{v} depends on u , the vector that points in the direction of increasing u is,

$$\mathbf{e}_u = \frac{\partial \mathbf{v}}{\partial u} \quad (1)$$

Identifying $x^1 = \theta$, $x^2 = r$ and $x^3 = z$, we compute the vector \mathbf{e}_i in order to obtain the elements of the covariant metric tensor $g_{ij} = \mathbf{e}_i \cdot \mathbf{e}_j$.



$$\mathbf{r} = (r \cdot \hat{\mathbf{x}}) \hat{\mathbf{x}} + (r \cdot \hat{\mathbf{y}}) \hat{\mathbf{y}}$$

$$\mathbf{r} = r \cos \theta \hat{\mathbf{x}} + r \sin \theta \hat{\mathbf{y}}$$

Thus, $\mathbf{R} = r \cos \theta \hat{\mathbf{x}} + r \sin \theta \hat{\mathbf{y}} + z \hat{\mathbf{z}}$, and the vectors \mathbf{e}_i are,

$$\mathbf{e}_\theta = \frac{\partial \mathbf{R}}{\partial \theta} = \frac{\partial}{\partial \theta} (r \cos \theta \hat{\mathbf{x}} + r \sin \theta \hat{\mathbf{y}} + z \hat{\mathbf{z}})$$

$$\mathbf{e}_\theta = -r \sin \theta \hat{\mathbf{x}} + r \cos \theta \hat{\mathbf{y}} \quad (2)$$

$$\mathbf{e}_r = \frac{\partial \mathbf{R}}{\partial r} = \frac{\partial}{\partial r} (r \cos \theta \hat{\mathbf{x}} + r \sin \theta \hat{\mathbf{y}} + z \hat{\mathbf{z}})$$

$$\mathbf{e}_r = \cos \theta \hat{\mathbf{x}} + \sin \theta \hat{\mathbf{y}} \quad (3)$$

$$\mathbf{e}_z = \frac{\partial \mathbf{R}}{\partial z} = \frac{\partial}{\partial z} (r \cos \theta \hat{\mathbf{x}} + r \sin \theta \hat{\mathbf{y}} + z \hat{\mathbf{z}})$$

$$\mathbf{e}_z = \hat{\mathbf{z}} \quad (4)$$

The cylindrical coordinate system is orthogonal, therefore $g_{ij} = 0 \forall i \neq j$. Accordingly,

$$g_{11} = \hat{\mathbf{e}}_\theta \cdot \hat{\mathbf{e}}_\theta = (-r \sin \theta \hat{\mathbf{x}} + r \cos \theta \hat{\mathbf{y}}) \cdot (-r \sin \theta \hat{\mathbf{x}} + r \cos \theta \hat{\mathbf{y}}) = r^2 \sin^2 \theta + r^2 \cos^2 \theta = \rightarrow g_{11} = r^2$$

$$g_{22} = \hat{\mathbf{e}}_r \cdot \hat{\mathbf{e}}_r = (\cos \theta \hat{\mathbf{x}} + \sin \theta \hat{\mathbf{y}}) \cdot (\cos \theta \hat{\mathbf{x}} + \sin \theta \hat{\mathbf{y}}) = \cos^2 \theta + \sin^2 \theta = \rightarrow g_{22} = 1$$

$$g_{33} = \hat{\mathbf{e}}_z \cdot \hat{\mathbf{e}}_z = \hat{\mathbf{z}} \cdot \hat{\mathbf{z}} = \rightarrow g_{33} = 1 \quad (5)$$

The “physical” components, $B_{\langle i \rangle} = \sqrt{g_{ii}} B^i$ become,

$$\begin{aligned}
 B_{\langle 1 \rangle} &= B_\theta = \sqrt{g_{11}} B^1 = \sqrt{r^2} B^1 \rightarrow B_{\langle 1 \rangle} = r B^1 \\
 B_{\langle 2 \rangle} &= B_r = \sqrt{g_{22}} B^2 = \sqrt{1} B^2 \rightarrow B_{\langle 2 \rangle} = B^2 \\
 B_{\langle 3 \rangle} &= B_z = \sqrt{g_{33}} B^3 = \sqrt{1} B^3 \rightarrow B_{\langle 3 \rangle} = B^3
 \end{aligned} \tag{6}$$

Be the equations (29)-(32),

$$q = x^1, \quad p = - \int \sqrt{g} B^3 dx^2, \quad t = x^3, \quad H = - \int \sqrt{g} B^1 dx^2. \tag{7}$$

where $g = g_{11} g_{22} g_{33}$. In cylindrical coordinates, $\sqrt{g} = \sqrt{r^2 \cdot 1 \cdot 1} = r$, $B^1 = B_\theta/r$, and,

$$q = \theta, \quad p = - \int r B_z dr, \quad t = z = R_0 \phi, \quad H = - \int B_\theta dr. \tag{8}$$